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# TORQUES AND RIEMANN'S MINIMAL SURFACES

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ABSTRACT. In this article, we prove that a properly embedded minimal surface in  $\mathbf{R}^3$  of genus zero must be one of Riemann's minimal examples if outside of a solid cylinder it is the union of planar ends with the same torques at all integer heights.

## 1. Introduction

An immersed surface in  $\mathbb{R}^3$  is said to be *minimal* if its mean curvature vanishes identically. In 1867, Riemann [7] used elliptic functions to classify all minimal surfaces in  $\mathbb{R}^3$  that are foliated by circles and straight lines in horizontal planes. He showed that these examples are the plane, the catenoid, the helicoid and one parameter family  $\{R_t\}_{t>0}$ with infinity topology. The new surfaces  $R_t$ , called Riemann's minimal surfaces, intersect horizontal planes in lines at precisely integer heights. We have more characterizations of  $R_t$  by:

(a) Each  $R_t$  is invariant under the reflection of  $\mathbf{R}^3$  in the  $(x_1, x_3)$ -plane and by the translation T by (t, 0, 2).

(b) In the complement of a solid cylinder of  $\mathbf{R}^3$ , the surface  $R_t$  consists of planar ends at integer heights. A planar end means that a properly embedded finite total curvature minimal annulus with compact boundary, which is asymptotic to the end of a plane.

(c) Each  $R_t$  is conformally equivalent to  $\mathbf{C}^* = \mathbf{C} \setminus \{0\}$  punctured in a discrete set of points with 0 and  $\infty$  being limit points of ends.

(d) The quotient surface  $R_t/T$  is a properly embedded finite total curvature minimal torus in  $\mathbf{R}^3/T$  with two planar ends.

In 2001, the author studied the characterization problem of Riemann's minimal surfaces without assuming periodicity and showed that:

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THEOREM 1.1. [2] Let M be a properly embedded minimal surface in  $\mathbb{R}^3$  of genus zero, which is the union of planar ends  $\{E_n\}_{n \in \mathbb{N}}$  outside of a solid cylinder, at integer heights. Suppose that it is symmetric by the reflection in a plane, and there is a number  $k \in \mathbb{Z}$  such that  $Torque(E_{n+2k}) = Torque(E_n)$  for all  $n \in \mathbb{Z}$ . Then M must be one of Riemann's minimal examples.

However, we realize that the assumption of the existence of symmetric plane is not necessarily, and can prove more elaborate result:

THEOREM 1.2 (Main Theorem). A properly embedded minimal surface in  $\mathbb{R}^3$  of genus zero is a Riemann's minimal example if it is the union of planar ends with the same torques at all integer heights in the complement of a solid cylinder.

Recall a torque vector of a closed curve points to the direction with the largest tendency of rotation of a surface in  $\mathbb{R}^3$  around the curve. In particular, for a minimal surface of  $\mathbb{R}^3$  the torque vector associated to a planar end whose Gauss map has ramification order 2, like as ends of  $R_t$ , describes the intersection of the surface with the limit affine tangent plane. Precisely, this intersection curve is asymptotic to a straight line in the direction of the torque. Recall in  $R_t$ , all of the torque vectors of the planar ends are the same. We use the maximum principle of a minimal surface and Liouville's theorem to prove that M is also periodic in such a setting. Then, by virtue of the previous result of Meeks, Pérez and Ros in [4], we can say that M is one of  $R_t$ .

# 2. Preliminaries

A minimal surface in the 3-dimensional Euclidean space is a conformal harmonic immersion  $X : \tilde{S} \hookrightarrow \mathbb{R}^3$  where  $\tilde{S}$  is a 2-dimensional smooth manifold, with or without boundary. The well known *Enneper-Weierstrass representation* of a minimal surface of  $\mathbb{R}^3$  follows that

(1) 
$$X(p) = \Re \int^{p} \left(\frac{1}{2}f(1-g^{2}), \frac{i}{2}f(1+g^{2}), fg\right) dz$$

where f is a holomorphic function and g is a meromorphic function on M, such that when a pole of order m of g occurs, f has a zero of order 2m, and this is the only case where f can vanish. In fact, g is the stereographic projection of the Gauss map of X with respect to the north

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pole. Applying Stoke's theorem to the isometric (minimal) immersion X we have

$$\int_{S} \Delta_{S} X \, dA = \int_{\partial S} \nu ds = 0$$

where S is a compact domain of  $\tilde{S}$ , dA is the element of area on S,  $\Delta_S$  is the Laplacian on S, ds is the line element on  $\partial S$ , and  $\nu$  is the outward conormal. Define the flux of X along a closed curve  $\gamma \subset S$  as

$$Flux(\gamma) := \int_{\gamma} \nu \, ds$$

which is well defined on the homology class of  $[\gamma]$ . Now let  $R_{\vec{u}}$  be the Killing field associated with counter-clockwise rotation about the axis  $\ell_{\vec{u}}$  in the  $\vec{u}$  direction, then

$$\int_{\partial S} R_{\vec{u}} \cdot \nu \, ds = \int_{\partial S} (X \wedge \nu) \cdot \vec{u} \, ds = 0.$$

This motivates defining the homologous invariant *torque* of a closed curve  $\gamma$  on S by

$$Torque_0(\gamma) := \int_{\gamma} X \wedge \nu.$$

In general, the torque is dependent on the base point of the position vector X. If we move the base point from 0 to  $W \in \mathbb{R}^3$ , then the position vector based on W is X - W, and the torque is that

(2) 
$$Torque_W(\gamma) = Torque_0(\gamma) - W \wedge \int_{\gamma} \nu$$
  
=  $Torque_0(\gamma) - W \wedge Flux(\gamma).$ 

Observe that we can define the flux and the torque associated to a planar end as that of one representative curve for the end.

#### 3. Proof of main theorem

Since M is a properly embedded minimal surface of genus zero with two limit ends, by [6], it has the conformal type  $\mathbf{C}^* \setminus K$  where K is the set of discrete punctures  $p_n \in \mathbf{C}^*$ ,  $n \in \mathbf{Z}$ , corresponding to the planar ends  $E_n$  at integer height  $x_3 = n$ , respectively. Now we define a conformal harmonic embedding of M by

$$X: \mathbf{C}^* \setminus K \to \mathbf{R}^3$$

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Let  $X = (X^1, X^2, X^3)$ . Since M cuts transversally any horizontal plane, we can say that;

$$X^3(z) = \frac{1}{\log r} \, \log |z|$$

for some r > 1. Moreover, except at integer heights, M meets a horizontal plane in a compact Jordan curve, and hence  $X^3$  can be continuously extended to the whole  $\mathbb{C}^*$ . In particular, since  $E_n$  is close to  $\{x_3 = n\}$ at infinity, we have  $X^3(p_n) = \frac{1}{\log r} \log |p_n| = n$  for all  $p_n \in K$ . It follows that  $|p_n| = r^n$  for all  $n \in \mathbb{Z}$ . If (g, f dz) is the Weierstrass-data of X, then from (1) we have;

(3) 
$$f(z) g(z) := 2 \frac{\partial X^3}{\partial z} = \frac{d}{dz} \left( \frac{1}{\log r} \log z \right) = \frac{1}{\log r} \frac{1}{z}$$

for all  $z \in \mathbf{C}^*$ . Since both z and dz have no zero or pole in  $\mathbf{C}^*$ , every planar end of M has the minimum branching order 2.

Let  $C_R \subset \mathbf{R}^3$  be a solid cylinder with sufficiently large radius R > 0such that M is the union of planar ends in complement of  $C_R$ , and let  $(s,t,1) \in \mathbf{R}^3$  be the direction of the axis line of the cylinder for some s,t > 0. Denote by  $\tilde{M}$  the translation of M along the direction 2(s,t,1). Since M and  $\tilde{M}$  are conformally equivalent, with another suitable coordinate  $\zeta$ , we have a minimal embedding

$$\tilde{X}: \mathbf{C}^* \setminus K \hookrightarrow \mathbf{R}^3$$

of  $\tilde{M}$  such that  $\tilde{X}^3(\zeta) = \frac{1}{\log r} \log |\zeta|$ . Therefore, we can say that

(4) 
$$X^3 \equiv \tilde{X}^3$$
 on  $\mathbf{C}^*$ 

Now let  $(\tilde{g}, \tilde{f}dz)$  be the Weierstrass data of X and  $\tilde{X}$ , then similar to (3), we have  $\tilde{f}(z) \tilde{g}(z) = \frac{1}{\log r} \frac{1}{z}$  for all  $z \in \mathbb{C}^*$ . Since all the planar ends have the minimum branching order 2, we have

$$g(z) = (z - p_n)^2 h(z), \quad \tilde{g}(z) = (z - p_n)^2 \tilde{h}(z)$$

on a sufficiently small neighborhood  $D_n \subset \mathbf{C}^*$  of  $p_n$ , where  $p_m \notin D_n$  if  $m \neq n$ , and h and  $\tilde{h}$  are the holomorphic functions on  $D_n$  with  $h(p_n) \neq 0$  and  $\tilde{h}(p_n) \neq 0$ . Therefore,

$$f(z) = \frac{1}{\log r} \frac{1}{z g(z)} = \frac{1}{\log r} \frac{1}{p_n h(p_n)} \frac{1}{(z - p_n)^2} + F(z)$$
$$\tilde{f}(z) = \frac{1}{\log r} \frac{1}{z \tilde{g}(z)} = \frac{1}{\log r} \frac{1}{p_n \tilde{h}(p_n)} \frac{1}{(z - p_n)^2} + \tilde{F}(z)$$

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where F and  $\tilde{F}$  are holomorphic functions on  $D_n$ , and hence from (1);

$$(X^{1} - i X^{2})(z) = \frac{-1}{2\log r} \frac{1}{p_{n} h(p_{n})} \frac{1}{z - p_{n}} + O(|z - p_{n}|)$$
$$(\tilde{X}^{1} - i\tilde{X}^{2})(z) = \frac{-1}{2\log r} \frac{1}{p_{n} \tilde{h}(p_{n})} \frac{1}{z - p_{n}} + O(|z - p_{n}|).$$

Take a representative curve  $\gamma_n$  for the planar end  $E_n$  of M by

$$\gamma_n(\theta) = \left( R\cos\theta, R\sin\theta, \frac{1}{R}(\gamma_n^1\cos\theta + \gamma_n^2\sin\theta) + O(R^{-2}) \right)$$

where  $0 \le \theta \le 2\pi$  and

$$\gamma_n^1 X^1 + \gamma_n^2 X^2 = \Re \left( \frac{1}{-2(\log r)^2 p_n^2 h(p_n)} (X^1 + iX^2) \right).$$

Then the conormal is  $\nu(\theta) = (\cos \theta, \sin \theta, 0) + O(R^{-2})$ , and so we can compute the flux  $Flux(E_n) = (0, 0, 0)$  and the torque by

$$Torque(E_n) = \pi(-\gamma_n^2, \gamma_n^1, 0) = -\frac{i\pi}{2(\log r)^2} \left( (\overline{p_n^2 h(p_n)})^{-1}, 0 \right)$$

which is independent of the base point, see (2). Similarly, the torque of the end  $\tilde{E}_n$  of  $\tilde{M}$  at the height  $x_3 = n$  is

$$Torque\left(\tilde{E}_{n}\right) = -\frac{i\pi}{2\left(\log r\right)^{2}}\left(\left(\overline{p_{n}^{2}\,\tilde{h}(p_{n})}\right)^{-1},\,0\right).$$

Since both  $E_n$  and  $\tilde{E}_n$  have the same torques,  $\tilde{h}(p_n) = h(p_n)$  and

$$(X^1 - i X^2)(z) - (\tilde{X}^1 - i \tilde{X}^2)(z) = O(|z - p_n|)$$

on the small neighborhood of  $p_n$ . Together with (4), it shows that each  $p_n \in K$  is the removable singularity of  $X - \tilde{X}$ . Hence, we can obtain the extended harmonic map

$$Y: \mathbf{C}^* \hookrightarrow \mathbf{R}^3$$

of  $X - \tilde{X}$  such that  $Y(p_n) = 0$  for all  $n \in \mathbb{Z}$ . Take a pairwise disjoint connected neighborhood  $U_n \subset \mathbb{C}^*$  of  $p_n, n \in \mathbb{Z}$ , respectively, such that both  $M \setminus \bigcup_{n \in \mathbb{Z}} X(U_n)$  and  $\tilde{M} \setminus \bigcup_{n \in \mathbb{Z}} \tilde{X}(U_n)$  are contained in  $C_R$ , then;

$$||Y(z)|| = ||(X^1 - iX^2)(z) - (\tilde{X}^1 - i\tilde{X}^2)(z)|| \le 2R\sqrt{1 + s^2 + t^2}$$

on  $\partial U_n$ . By the maximum principle of the harmonic map, we have;

$$||Y|| \le 2R\sqrt{1+s^2+t^2} \quad \text{on } U_n$$

for all  $n \in \mathbb{Z}$ . By the definition of  $U_n$ , the above inequality also holds in the complement of  $\bigcup_{n \in \mathbb{Z}} U_n$ , so Y is a bounded harmonic map on the

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punctured plane  $\mathbb{C}^*$ . By virtue of the Liouville's theorem, Y is then a constant map  $Y \equiv 0$  by  $Y(p_n) = 0$ . Hence  $M = \tilde{M}$  and M is periodic under a translation. However, we know the result of [4]: A properly periodic embedded minimal annulus in  $\mathbb{R}^3$  must be one of Riemann's minimal examples. Thus M is also one of Riemann's minimal examples, and we have proved the theorem.

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